

2.5 PROPERTIES OF LAPLACE TRANSFORM

1. Linearity:

Statement:

If $x_1(t) \xleftrightarrow{\mathcal{L}} X_1(s)$ with a region of convergence denoted as R_1

and $x_2(t) \xleftrightarrow{\mathcal{L}} X_2(s)$ with a region of convergence denoted as R_2

then $ax_1(t) + bx_2(t) \xleftrightarrow{\mathcal{L}} aX_1(s) + bX_2(s)$, with ROC containing $R_1 \cap R_2$

Proof:

$$\begin{aligned}\mathcal{L}\{z(t)\} &= \mathcal{L}\{ax_1(t) + bx_2(t)\} = \int_{-\infty}^{\infty} \{ax_1(t) + bx_2(t)\}e^{-st} dt \\ &= a \int_{-\infty}^{\infty} x_1(t)e^{-st} dt + b \int_{-\infty}^{\infty} x_2(t)e^{-st} dt \\ &= aX_1(s) + bX_2(s)\end{aligned}$$

2. Time Shifting:

Statement:

If $x(t) \xleftrightarrow{\mathcal{L}} X(s)$ with ROC = R

then $x(t - \tau) \xleftrightarrow{\mathcal{L}} e^{-s\tau} X(s)$ with ROC = R

Proof:

$$\mathcal{L}\{x(t - \tau)\} = \int_{-\infty}^{\infty} x(t - \tau)e^{-st} dt$$

Let $t - \tau = p$

$$\begin{aligned}&= \int_{-\infty}^{\infty} x(p)e^{-s(p+\tau)} dt \\ &= e^{-s\tau} \int_{-\infty}^{\infty} x(p)e^{-sp} dt \\ &= e^{-s\tau} X(s)\end{aligned}$$

3. Shifting in s-Domain:

Statement:

If $x(t) \xleftrightarrow{\mathcal{L}} X(s)$ with $\text{ROC} = R$

then $e^{s_0 t} x(t) \xleftrightarrow{\mathcal{L}} X(s - s_0)$ with $\text{ROC} = R + \text{Re}\{s_0\}$

Proof:

$$\begin{aligned}\mathcal{L}\{e^{s_0 t} x(t)\} &= \int_{-\infty}^{\infty} e^{s_0 t} x(t) e^{-st} dt \\ &= \int_{-\infty}^{\infty} x(t) e^{-(s-s_0)t} dt \\ &= X(s - s_0)\end{aligned}$$

4. Time Scaling:

Statement:

If $x(t) \xleftrightarrow{\mathcal{L}} X(s)$ with $\text{ROC} = R$

then $x(at) \xleftrightarrow{\mathcal{L}} \frac{1}{|a|} X\left(\frac{s}{a}\right)$ with $\text{ROC} = R_1 = aR$

Proof:

Case 1: For $a > 0$:

$$\mathcal{L}\{x(at)\} = \int_{-\infty}^{\infty} x(at) e^{-st} dt$$

Using the substitution of $\lambda = at$; $dt = a d\lambda$

$$\begin{aligned}&= \frac{1}{a} \int_{-\infty}^{\infty} x(\lambda) e^{-\left(\frac{s}{a}\right)\lambda} d\lambda \\ &= \frac{1}{a} X\left(\frac{s}{a}\right)\end{aligned}$$

Case 2: For $a < 0$:

$$\mathcal{L}\{x(at)\} = \int_{-\infty}^{\infty} x(at) e^{-st} dt$$

Using the substitution of $\lambda = at$; $dt = a d\lambda$

$$= -\frac{1}{a} \int_{-\infty}^{\infty} x(\lambda) e^{-\left(\frac{s}{a}\right)\lambda} d\lambda$$

$$= -\frac{1}{a} X\left(\frac{s}{a}\right)$$

Combining the two cases, we get $x(at) \xleftrightarrow{\mathcal{L}} \frac{1}{|a|} X\left(\frac{s}{a}\right)$ with $\text{ROC} = R_1 = aR$

5. Conjugation:

Statement:

If $x(t) \xleftrightarrow{\mathcal{L}} X(s)$ with $\text{ROC} = R$

then $x^*(t) \xleftrightarrow{\mathcal{L}} X^*(s^*)$ with $\text{ROC} = R$

Proof:

$$\mathcal{L}\{x^*(t)\} = \int_{-\infty}^{\infty} x^*(t) e^{-st} dt$$

$\therefore s = \sigma + j\omega$

$$= \int_{-\infty}^{\infty} x^*(t) e^{-\sigma t} e^{-j\omega t} dt$$

$$= \left(\int_{-\infty}^{\infty} x(t) e^{-\sigma t} e^{j\omega t} dt \right)^*$$

$$= \left(\int_{-\infty}^{\infty} x(t) e^{-(\sigma - j\omega)t} dt \right)^*$$

$$= \left(\int_{-\infty}^{\infty} x(t) e^{-(s^*)t} dt \right)^*$$

$$= (X(s^*))^* = X^*(s^*)$$

6. Convolution Property:**Statement:**If $x_1(t) \xleftrightarrow{\mathcal{L}} X_1(s)$ with ROC = R_1 and $x_2(t) \xleftrightarrow{\mathcal{L}} X_2(s)$ with ROC = R_2 then $x_1(t) * x_2(t) \xleftrightarrow{\mathcal{L}} X_1(s).X_2(s)$, with ROC containing $R_1 \cap R_2$ **Proof:**

$$\begin{aligned}
 \mathcal{L}\{z(t)\} &= \mathcal{L}\{x_1(t) * x_2(t)\} = \int_{-\infty}^{\infty} \{x_1(t) * x_2(t)\} e^{-st} dt \\
 &= \int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} x_1(\tau) x_2(t - \tau) d\tau \right\} e^{-st} dt \\
 \mathcal{L}\{x_1(t) * x_2(t)\} &= \int_{-\infty}^{\infty} x_1(\tau) \left\{ \int_{-\infty}^{\infty} x_2(t - \tau) e^{-st} dt \right\} d\tau \\
 &= \int_{-\infty}^{\infty} x_1(\tau) \{e^{-s\tau} X_2(s)\} d\tau \\
 &= X_2(s) \int_{-\infty}^{\infty} x_1(\tau) e^{-s\tau} d\tau \\
 &= X_1(s).X_2(s)
 \end{aligned}$$

7. Differentiation in the Time Domain:**Statement:**If $x(t) \xleftrightarrow{\mathcal{L}} X(s)$ with ROC = R then $\frac{dx(t)}{dt} \xleftrightarrow{\mathcal{L}} s X(s)$ with ROC containing R **Proof:**

Inverse Laplace transform is given by

$$x(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} X(s) e^{st} ds$$

Differentiating above on both sides with respect to 't'

$$\frac{dx(t)}{dt} = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} \{sX(s)\} e^{st} ds$$

Comparing both equations $sX(s)$ is the Laplace transform of $\frac{dx(t)}{dt}$.

8. Differentiation in the s-Domain:

Statement:

If $x(t) \xleftrightarrow{\mathcal{L}} X(s)$ with $\text{ROC} = R$

then $-tx(t) \xleftrightarrow{\mathcal{L}} \frac{dX(s)}{ds}$ with $\text{ROC} = R$

Proof:

Laplace transform is given by

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

Differentiating above on both sides with respect to 's'

$$\frac{dX(s)}{ds} = \int_{-\infty}^{\infty} \{-tx(t)\} e^{-st} dt$$

Comparing both equations $\frac{dX(s)}{ds}$ is the Laplace transform of $-tx(t)$.

9. Integration in the Time Domain:

Statement:

If $x(t) \xleftrightarrow{\mathcal{L}} X(s)$ with $\text{ROC} = R$

then $\int_{-\infty}^t x(\tau) d\tau \xleftrightarrow{\mathcal{L}} \frac{1}{s} X(s)$ with ROC containing $R \cap \{\text{Re}\{s\} > 0\}$

Proof:

$$\int_{-\infty}^t x(\tau) d\tau = x(t) * u(t)$$

$$\mathcal{L}\left\{\int_{-\infty}^t x(\tau) d\tau\right\} = \mathcal{L}\{x(t) * u(t)\} = X(s) \cdot \mathcal{L}\{u(t)\} = X(s) \frac{1}{s}$$

10.The Initial and Final Value Theorems:

Statement:

If $x(t)$ and $\frac{dx(t)}{dt}$ are Laplace transformable, and under the specific constraints that $x(t)=0$ for $t<0$ containing no impulses at the origin, one can directly calculate, from the

Laplace transform, the initial value $x(0^+)$, i.e., $x(t)$ as t approaches zero from positive values of t . Specifically the *initial -value theorem* states that

$$x(0^+) = \lim_{s \rightarrow \infty} sX(s)$$

Also, if $x(t)=0$ for $t<0$ and, in addition, $x(t)$ has a finite limit as $t \rightarrow \infty$, then the *final-value theorem* says that

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$$

