CONVOLUTION INTEGRAL

The response of a continuous-time LTI system can be computed by convolution of the impulse response of the system with the input signal, using a convolution integral, rather than a sum.

The response to the input signal x(t) can be written as a convolution integral:

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau$$

or it can be expressed symbolically

$$y(t)=x(t)*h(t)$$

Calculation of convolution integral

The output y(t) is a weighted integral of the input, where the weight on $x(\tau)$ is $h(t-\tau)$ To evaluate this integral for a specific value of t,

· First obtain the signal $h(t - \tau)$ (regarded as a function of τ with t fixed) from $h(\tau)$ by

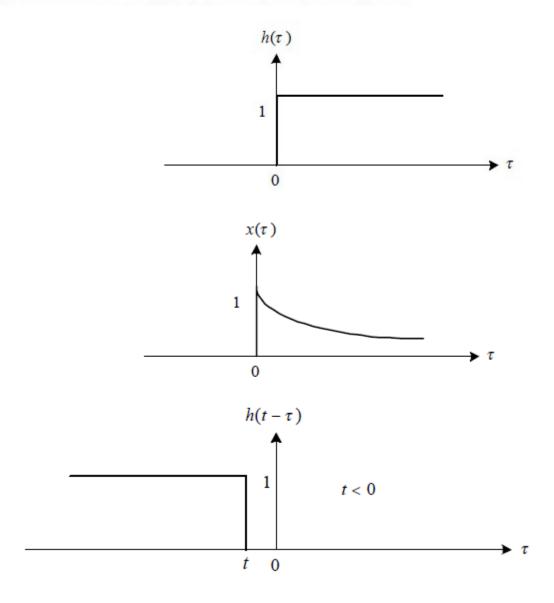
a reflection about the origin and a shift to the right by t if t>0 or a shift to the left by MS is t<0. Then multiply together the signals $x(\tau)$ and $h(t-\tau)$. y(t) is obtained by integrating the resulting product from $\tau=-\infty$ to $\tau=+\infty$

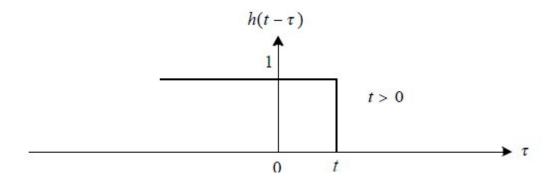
 $\label{eq:example:Letx} Example: Letx(t) \ be \ the \ input \ to \ an \ LTI \ system \ with \ unit \ impulse \ response \ h(t) \ ,$ where

$$x(t) = e^{-at}u(t)$$
, $a > 0$ and $h(t) = u(t)$.

Solution:

Step1: The functions $h(\tau)$, $x(\tau)$ and $h(t-\tau)$ are depicted





Step 2: From the figure we can see that for t < 0, the product of the product $x(\tau)$ and $h(t - \tau)$ is zero, and consequently, y(t) is zero. For t > 0

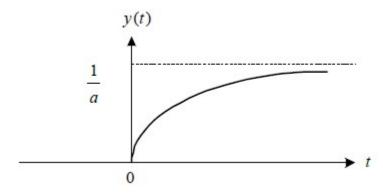
$$x(\tau)h(t-\tau) = \begin{cases} e^{-at}, & t > 0\\ 0, & otherwise \end{cases}$$

Step 3: Compute y(t) by integrating the product for t > 0

$$y(t) = \int_0^t e^{-a\tau} d\tau = -\frac{1}{a} e^{-a\tau} \Big|_0^t = \frac{1}{a} (1 - e^{-at}).$$

The output of y(t) for all t is

 $y(t) = \frac{1}{a}(1 - e^{-at})u(t)$, and is shown in figure below.



Example: Compute the convolution of the two signals below:

$$x(t) = \begin{cases} 1, & 0 < t < T \\ 0, & otherwise \end{cases} \text{ and } h(t) = \begin{cases} t, & 0 < t < 2T \\ 0, & otherwise \end{cases}$$

Solution:

