

Steady State refers to a condition where the current & voltage waveforms are stable repeating sinusoids with a constant amplitude, frequency & phase shift.

(b) There are no transient changes occurring & the circuit has reached a predictable, unchanging state after any initial fluctuations have subsided.

Transient response is the initial response of a system to a sudden change in i/p, before it settles down to a steady state.

Steady State Current is a constant current that does not change over time. It is a type of Direct Current (DC).

Unit III Sinusoidal Steady State Analysis.

All the electrical systems operate with alternating voltages & current. Hence it is important to analyze the steady state conditions.

AC Fundamentals

Sinusoidal Alternating Quantity

- * An Alternating Quantity which varies according to the sine of the angle θ is known as sinusoidal alternating quantity.
- * In our world, sinusoidal voltages & currents are selected for generation of electrical power.

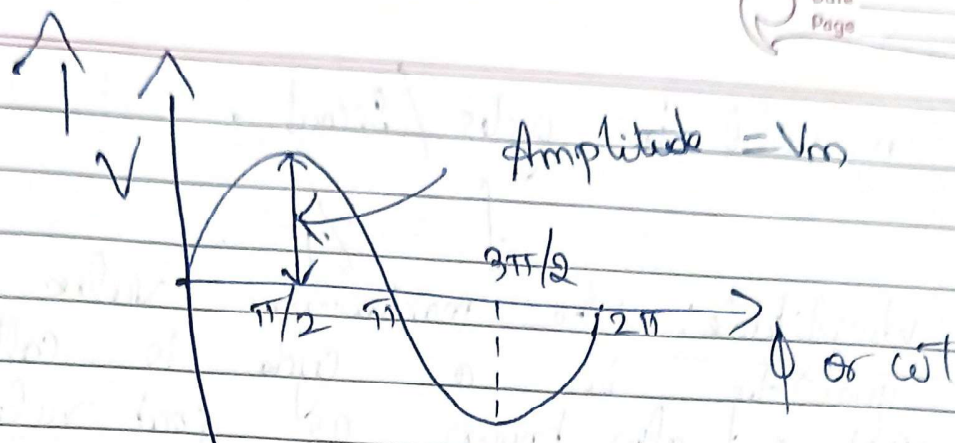
Reason for using Sinusoidal voltages / Current

- * Produces low iron & coil losses in AC rotating machines & transformers.
- * It improves efficiency.
- * After less interference to nearby telephone lines.
- * Produces less disturbance in electrical circuit.

Characteristics of Sinusoids.

Sinusoidal Voltages: $V = V_m (\sin \omega t + \phi)$

Sinusoidal Current: $I = I_m (\sin \omega t + \phi)$



$$V = V_m \sin \phi$$

Sinusoidal Signal

Where

ω = Angular frequency in rad/sec.

ϕ = Phase angle.

V = Instantaneous Voltage in Volts.

I = Instantaneous Current in A.

V_m = Maximum Voltage

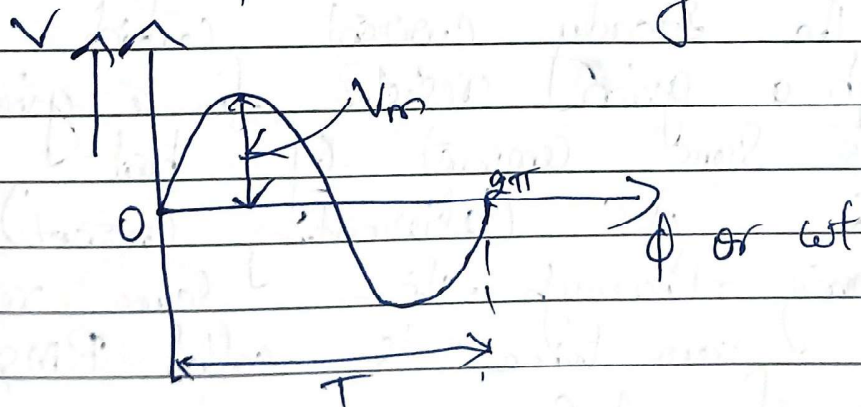
I_m = Maximum Current

Cycle:

It is a set of positive & negative portions of a waveform.

Time Period:

The time required for an alternating quantity to complete one cycle is called time period denoted by T .



Frequency:

The number of cycles per second is frequency & it is denoted by f . It is

measured in cycles / second.

$$f = 1/T$$

Amplitude: The maximum value of alternating quantity in a cycle is called amplitude. It is also known as peak value / crest value. In voltage waveform peak value is V_m . It occurs at $\pi/2$ & $3\pi/2$.

Relation between ω & f

Angular distance = Angular velocity $\times$ Time

$$\theta = \omega \times t$$

$\theta = 360^\circ = 2\pi$ radians, one cycle is completed.

$$2\pi = \omega t$$

$t \rightarrow$ Time taken for completion of one cycle.

$$\omega = 2\pi / T$$
$$\omega = 2\pi f$$

AC $\rightarrow$ heat
DC $\rightarrow$ heat

Root Mean Square / Effective value

(Average value of AC waveform)

The steady current which when flowing through a given resistor for a given time produces same amount of heat as produced by the A.C (alternating current), when flowing through the same resistor for the same time is called Rms / effective value of A.C.

Methods to find RMS Value: Analytical Method

$$I_{RMS}^2 = \frac{1}{2\pi} \int_0^{2\pi} i^2 d\theta = \frac{1}{T} \int_0^T i^2 dt \Rightarrow$$

$$I_{RMS}^2 = \frac{1}{\pi} \int_0^{\pi} i^2 d\theta = \frac{2}{T} \int_0^{T/2} i^2 dt \Rightarrow$$

Unsymmetrical waveform

Symmetrical waveform

RMS Value of Sinusoidal Alternating Quantity

$$i = I_m \sin \theta \Rightarrow \text{Symmetrical Waveform}$$
$$I_{RMS}^2 = \frac{1}{\pi} \int_0^{\pi} i^2 d\theta = \frac{1}{\pi} \int_0^{\pi} I_m^2 \sin^2 \theta d\theta$$

$$= \frac{1}{\pi} I_m^2 \int_0^{\pi} \left(\frac{1 - \cos 2\theta}{2} \right) d\theta$$

$$= \frac{1}{\pi} I_m^2 \left[\frac{1}{2} [\theta]_0^{\pi} - \frac{1}{2} [\sin 2\theta]_0^{\pi} \right]$$

$$\left[\because \sin 2\pi = \sin 0 = 0 \right]$$

$$= \frac{1}{\pi} I_m^2 \frac{1}{2} [(\pi - 0) - 0]$$

$$I_{RMS}^2 = I_m^2 / 2$$

$$I_{RMS} = I_m / \sqrt{2} \Rightarrow 0.707 I_m$$

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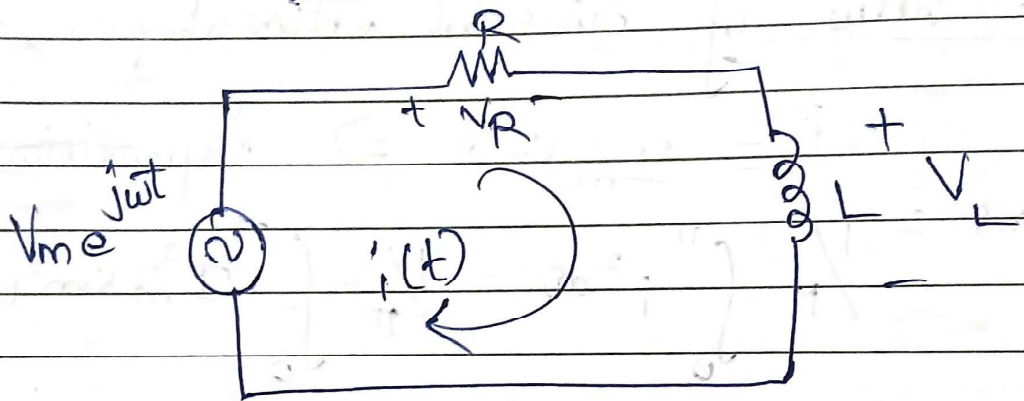
$$\text{RMS Value} = 0.707 \times \text{Max Value}$$

$$\text{RMS value} = \sqrt{\frac{\text{Area of the Squared Curve}}{\text{Base}}}$$

3.2 Complex Forcing Functions

Euler's identity gives Sinusoidal & exponentials as related through complex numbers.

$$e^{j\theta} = \cos \theta + j \sin \theta$$



Basic first order circuit.

$$V_m e^{j\omega t} = V_m \cos(\omega t) + j V_m \sin \omega t$$

Apply KVL to the above circuit:

$$V_L + V_R - V_m e^{j\omega t} = 0$$

$$L \frac{di(t)}{dt} + R i(t) = V_m e^{j\omega t} \quad \text{--- (1)}$$

$$\text{Let } i(t) = I_m e^{j(\omega t + \phi)}$$

$$\frac{di(t)}{dt} = j\omega I_m e^{j(\omega t + \phi)} \quad \text{--- (2)}$$