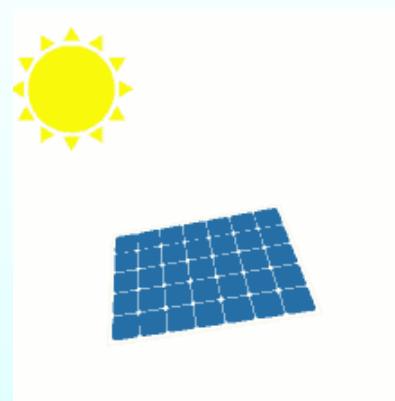


DC – Transient Response of RLC Series Circuit



Rohini College of Engineering and Technology



DC Response of RLC Series Circuit :

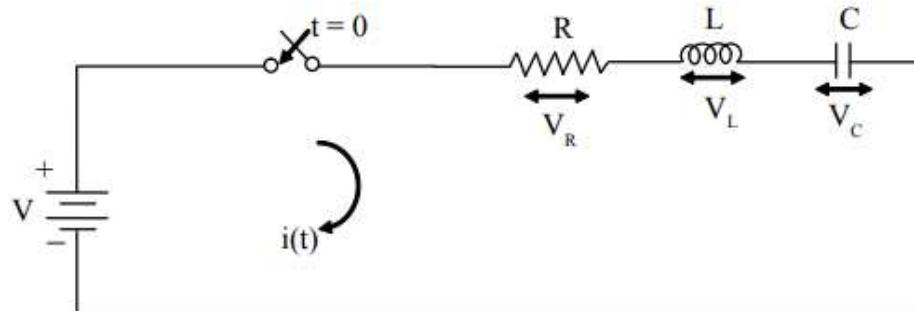


Fig. 4.10 RLC series circuit

The RLC series circuit is shown above which is excited by a DC source. Assume that at $t = 0$, the switch S is closed. While closing the switch, the voltage drop across the capacitor and current flowing through the inductor is zero.

Applying KVL to the circuit,

$$V = V_R(t) + V_L(t) + V_C(t)$$

$$V = Ri(t) + L \frac{di(t)}{dt} + \frac{1}{C} \int i(t) dt \quad \text{-----(13)}$$

By applying laplace transform to equation (13), we get

$$\frac{V}{S} = RI(s) + L \left[SI(s) - I(0) \right] + \frac{1}{C} \left[\frac{I(s)}{S} + \frac{q(0)}{S} \right]$$

$$\text{Assume } I(0) = q(0) = 0$$



$$\therefore \frac{V}{S} = RI(S) + LSI(S) + \frac{I(S)}{CS}$$

$$= I(S) \left[R + LS + \frac{1}{CS} \right]$$

$$\frac{V}{S} = I(S) \left[\frac{RCS + LS^2C + 1}{CS} \right] = I(S) \left[\frac{S^2LC + RCS + 1}{CS} \right]$$

$$V = I(S) \left[\frac{S^2LC + SRC + 1}{C} \right]$$

$$V = I(S) \frac{LC}{C} \left[S^2 + \frac{SR}{L} + \frac{1}{LC} \right]$$

$$\therefore I(S) = \frac{V}{L \left[S^2 + \frac{R}{L}S + \frac{1}{LC} \right]} \quad \text{-----(14)}$$



The roots of the denominator for equation (14)

$$S_1, S_2 = \frac{-R/L \pm \sqrt{\left(\frac{R}{L}\right)^2 - \frac{4}{LC}}}{2 \times 1}$$
$$= \frac{-R}{2L} \pm \sqrt{\frac{R^2}{4L^2} - \frac{1}{LC}}$$
$$S_1, S_2 = \frac{-R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}} \quad \text{-----(15)}$$

Equation (15) can be represented by

$$S_1, S_2 = \alpha \pm \beta$$

where, $\alpha = \frac{-R}{2L}$ and $\beta = \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$

Here, $S_1 = \alpha + \beta, \quad S_2 = \alpha - \beta$



The natural frequency, $\omega_n = \frac{1}{\sqrt{LC}}$

Equation (14) can be written as

$$I(s) = \frac{\sqrt{L}}{(s - s_1)(s - s_2)}$$

$$\text{i.e., } I(s) = \frac{\sqrt{L}}{[s - (\alpha + \beta)][s - (\alpha - \beta)]} \quad \text{-----(16)}$$

There are three possibilities.

$$\text{Case 1 : when } \left(\frac{R}{2L}\right)^2 > \frac{1}{LC}$$

The two roots are real and distinct. The denominator has the roots $(\alpha + \beta)$ and $(\alpha - \beta)$ and we may write

$$I(s) = \frac{k_1}{s - (\alpha + \beta)} + \frac{k_2}{s - (\alpha - \beta)}$$

Taking inverse laplace transform,

$$\begin{aligned} i(t) &= k_1 e^{(\alpha+\beta)t} + k_2 e^{(\alpha-\beta)t} \\ &= e^{\alpha t} [k_1 e^{\beta t} + k_2 e^{-\beta t}] \quad \text{-----(17)} \end{aligned}$$

The value of k_1 and k_2 can be find by using partial fraction method. The current is said to be overdamped as in below fig. 4.11.

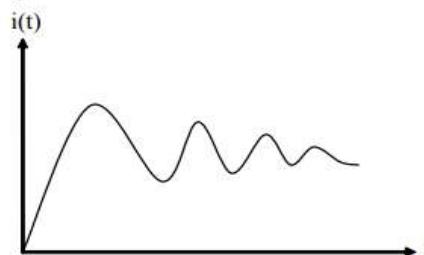


Fig. 3.11 Overdamped response

Case 2 : When $\left(\frac{R}{2L}\right)^2 = \frac{1}{LC}$

The root are equal and the oscillation in the circuit are just eliminated. The solution is the critically damped case.

$$I(S) = \frac{k_1}{(s-\alpha)^2} + \frac{k_2}{(s-\alpha)}$$

Taking inverse laplace transform,

$$i(t) = k_1 t e^{\alpha t} + k_2 e^{\alpha t} = e^{\alpha t} [k_1 t + k_2]$$

The current response of $i(t)$ for critically damped case is shown below.

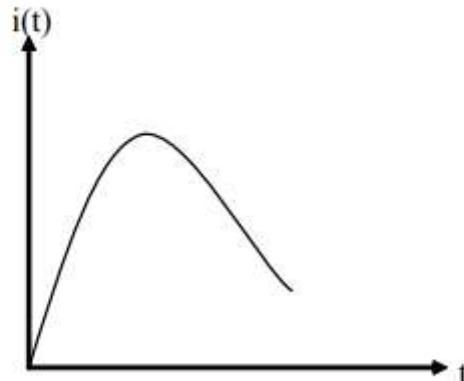


Fig. 3.12 Critically damped response

Case 3 :

$$\text{When } \left(\frac{R}{2L}\right)^2 < \frac{1}{LC}$$

The roots are complex conjugate and the circuit is under damped as shown below.

$$I(S) = \frac{k_1}{s - (\alpha + j\beta)} + \frac{k_2}{s - (\alpha - j\beta)}$$

Taking inverse laplace transform,

$$i(t) = k_1 e^{(\alpha+j\beta)t} + k_2 e^{(\alpha-j\beta)t}$$

$$= e^{\alpha t} [k_1 e^{j\beta t} + k_2 e^{-j\beta t}]$$

Where, k_1 and k_2 are complex and are also conjugate of one another.

$$k_2 = k_1^*$$

$$\therefore i \text{ can be rewritten as, } i = e^{\alpha t} [A \cos \beta t + B \sin \beta t]$$

This solution shows that the current is oscillatory and at the same time decays in a short time as $\alpha = -R/2L$ is always negative.

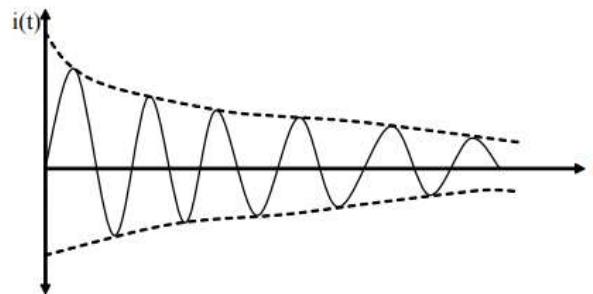


Fig. 3.13 Oscillatory response

Note : When the terms $\left(\frac{R}{2L}\right)^2$ and $\frac{1}{LC}$ are equal the oscillations are just eliminated and this condition is called “critical damping”.

Thank You

