

## 2.2 Graph Representation Methods

Graph representation methods describe how a graph is stored in computer memory so that graph algorithms (BFS, DFS, Dijkstra, etc.) can be executed efficiently.

The two main graph representation methods are:

1. Adjacency Matrix
2. Adjacency List
3. Edge List
4. Incidence Matrix

### 1. Adjacency Matrix

#### Definition

An adjacency matrix is a 2D array (matrix) of size  $n \times n$ , where  $n$  is the number of vertices in the graph.

$$A[i][j] = \begin{cases} 1 & \text{if there is an edge from } i \text{ to } j \\ 0 & \text{otherwise} \end{cases}$$

#### Example

Consider an undirected graph:

A — B

| |

C — D

Vertices: A, B, C, D

Adjacency Matrix:

**A B C D**

A 0 1 1 0

B 1 0 0 1

C 1 0 0 1

D 0 1 1 0

### Directed Graph Case

- $A[i][j] = 1 \rightarrow$  edge from  $i$  to  $j$
- $A[j][i]$  may be 0

### Weighted Graph Case

- Matrix stores **weights instead of 1**

Example:

$$A[i][j] = \text{weight of edge}$$

### Time and Space Complexity

- **Space:**  $O(n^2)$
- **Edge lookup:**  $O(1)$

### Advantages

- ✓ Very simple to implement
- ✓ Fast edge existence checking
- ✓ Useful for dense graphs

### Disadvantages

- ✗ High memory usage
- ✗ Inefficient for sparse graphs

### Applications

- Dense networks
- Small graphs
- Graph algorithms in theory

## 2. Adjacency List

### Definition

An adjacency list stores a list of neighbors for each vertex.

### Example

Graph:

A — B

| |

C — D

Adjacency List:

A → B, C

B → A, D

C → A, D

D → B, C

### Directed Graph Case

- Only outgoing neighbors stored

### Weighted Graph Case

- Store (neighbor, weight) pairs

Example:

A → (B,5), (C,3)

### Time and Space Complexity

- **Space:**  $O(V + E)$
- **Edge lookup:**  $O(\text{degree})$

### Advantages

- ✓ Memory efficient
- ✓ Ideal for sparse graphs
- ✓ Used in BFS, DFS, Dijkstra

### Disadvantages

- ✗ Slower edge lookup
- ✗ Slightly complex implementation

## Applications

- Social networks
- Web graphs
- Large-scale graphs

## 3. Edge List

### Definition

An edge list stores all edges as pairs (or triples for weighted graphs).

### Example

Edge List:

(A, B)

(A, C)

(B, D)

(C, D)

Weighted:

(A, B, 5)

### Complexity

- **Space:**  $O(E)$
- **Edge lookup:**  $O(E)$

### Advantages

- ✓ Very simple
- ✓ Easy to read and store

### Disadvantages

- ✗ Very slow for traversal
- ✗ Not suitable for most algorithms

## Applications

- Kruskal's algorithm
- Graph input/output

## 4. Incidence Matrix

### Definition

An incidence matrix is a matrix where:

- Rows represent vertices
- Columns represent edges

### Example

Graph with edges  $e_1, e_2$ :

**$e_1 \ e_2$**

A 1 0

B 1 1

C 0 1

### Directed Graph Case

- +1 for outgoing edge
- -1 for incoming edge

### Complexity

- **Space:**  $O(V \times E)$

### Advantages

✓ Useful in mathematical analysis

### Disadvantages

- ✗ Very high space usage
- ✗ Rarely used in practice

## **Applications**

- Network flow theory
- Electrical circuits