

## 2.5 PROPERTIES OF LAPLACE TRANSFORM

### 1. Linearity:

**Statement:**

If  $x_1(t) \xleftrightarrow{\mathcal{L}} X_1(s)$  with a region of convergence denoted as  $R_1$

and  $x_2(t) \xleftrightarrow{\mathcal{L}} X_2(s)$  with a region of convergence denoted as  $R_2$

then  $ax_1(t) + bx_2(t) \xleftrightarrow{\mathcal{L}} aX_1(s) + bX_2(s)$ , with ROC containing  $R_1 \cap R_2$

**Proof:**

$$\begin{aligned} \mathcal{L}\{z(t)\} &= \mathcal{L}\{ax_1(t) + bx_2(t)\} = \int_{-\infty}^{\infty} \{ax_1(t) + bx_2(t)\}e^{-st} dt \\ &= a \int_{-\infty}^{\infty} x_1(t)e^{-st} dt + b \int_{-\infty}^{\infty} x_2(t)e^{-st} dt \\ &= aX_1(s) + bX_2(s) \end{aligned}$$

### 2. Time Shifting:

**Statement:**

If  $x(t) \xleftrightarrow{\mathcal{L}} X(s)$  with ROC = R

then  $x(t - \tau) \xleftrightarrow{\mathcal{L}} e^{-s\tau} X(s)$  with ROC = R

**Proof:**

$$\mathcal{L}\{x(t - \tau)\} = \int_{-\infty}^{\infty} x(t - \tau)e^{-st} dt$$

Let  $t - \tau = p$

$$= \int_{-\infty}^{\infty} x(p)e^{-s(p+\tau)} dt$$

$$= e^{-s\tau} \int_{-\infty}^{\infty} x(p)e^{-sp} dt$$

$$= e^{-s\tau} X(s)$$

**3. Shifting in s-Domain:****Statement:**If  $x(t) \stackrel{\mathcal{L}}{\leftrightarrow} X(s)$  with  $\text{ROC} = R$ then  $e^{s_0 t} x(t) \stackrel{\mathcal{L}}{\leftrightarrow} X(s - s_0)$  with  $\text{ROC} = R + \text{Re}\{s_0\}$ **Proof:**

$$\begin{aligned} \mathcal{L}\{e^{s_0 t} x(t)\} &= \int_{-\infty}^{\infty} e^{s_0 t} x(t) e^{-st} dt \\ &= \int_{-\infty}^{\infty} x(t) e^{-(s-s_0)t} dt \\ &= X(s - s_0) \end{aligned}$$

**4. Time Scaling:****Statement:**If  $x(t) \stackrel{\mathcal{L}}{\leftrightarrow} X(s)$  with  $\text{ROC} = R$ then  $x(at) \stackrel{\mathcal{L}}{\leftrightarrow} \frac{1}{|a|} X\left(\frac{s}{a}\right)$  with  $\text{ROC} = R_1 = aR$ **Proof:**Case 1: For  $a > 0$ :

$$\mathcal{L}\{x(at)\} = \int_{-\infty}^{\infty} x(at) e^{-st} dt$$

Using the substitution of  $\lambda = at$ ;  $dt = a d\lambda$ 

$$\begin{aligned} &= \frac{1}{a} \int_{-\infty}^{\infty} x(\lambda) e^{-\left(\frac{s}{a}\right)\lambda} d\lambda \\ &= \frac{1}{a} X\left(\frac{s}{a}\right) \end{aligned}$$

Case 2: For  $a < 0$ :

$$\mathcal{L}\{x(at)\} = \int_{-\infty}^{\infty} x(at) e^{-st} dt$$

Using the substitution of  $\lambda = at$ ;  $dt = a d\lambda$

$$= -\frac{1}{a} \int_{-\infty}^{\infty} x(\lambda) e^{-\left(\frac{s}{a}\right)\lambda} d\lambda$$

$$= -\frac{1}{a} X\left(\frac{s}{a}\right)$$

Combining the two cases, we get  $x(at) \stackrel{\mathcal{L}}{\leftrightarrow} \frac{1}{|a|} X\left(\frac{s}{a}\right)$  with  $\text{ROC} = R_1 = aR$

### 5. Conjugation:

**Statement:**

If  $x(t) \stackrel{\mathcal{L}}{\leftrightarrow} X(s)$  with  $\text{ROC} = R$

then  $x^*(t) \stackrel{\mathcal{L}}{\leftrightarrow} X^*(s^*)$  with  $\text{ROC} = R$

**Proof:**

$$\mathcal{L}\{x^*(t)\} = \int_{-\infty}^{\infty} x^*(t) e^{-st} dt$$

$\therefore s = \sigma + j\omega$

$$= \int_{-\infty}^{\infty} x^*(t) e^{-\sigma t} e^{-j\omega t} dt$$

$$= \left( \int_{-\infty}^{\infty} x(t) e^{-\sigma t} e^{j\omega t} dt \right)^*$$

$$= \left( \int_{-\infty}^{\infty} x(t) e^{-(\sigma - j\omega)t} dt \right)^*$$

$$= \left( \int_{-\infty}^{\infty} x(t) e^{-(s^*)t} dt \right)^*$$

$$= (X(s^*))^* = X^*(s^*)$$

**6. Convolution Property:****Statement:**If  $x_1(t) \xleftrightarrow{\mathcal{L}} X_1(s)$  with ROC =  $R_1$ and  $x_2(t) \xleftrightarrow{\mathcal{L}} X_2(s)$  with ROC =  $R_2$ then  $x_1(t) * x_2(t) \xleftrightarrow{\mathcal{L}} X_1(s) \cdot X_2(s)$ , with ROC containing  $R_1 \cap R_2$ **Proof:**

$$\begin{aligned} \mathcal{L}\{z(t)\} &= \mathcal{L}\{x_1(t) * x_2(t)\} = \int_{-\infty}^{\infty} \{x_1(t) * x_2(t)\} e^{-st} dt \\ &= \int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} x_1(\tau) x_2(t - \tau) d\tau \right\} e^{-st} dt \end{aligned}$$

$$\mathcal{L}\{x_1(t) * x_2(t)\} = \int_{-\infty}^{\infty} x_1(\tau) \left\{ \int_{-\infty}^{\infty} x_2(t - \tau) e^{-st} dt \right\} d\tau$$

$$= \int_{-\infty}^{\infty} x_1(\tau) \{e^{-s\tau} X_2(s)\} d\tau$$

$$= X_2(s) \int_{-\infty}^{\infty} x_1(\tau) e^{-s\tau} d\tau$$

$$= X_1(s) \cdot X_2(s)$$

**7. Differentiation in the Time Domain:****Statement:**If  $x(t) \xleftrightarrow{\mathcal{L}} X(s)$  with ROC =  $R$ then  $\frac{dx(t)}{dt} \xleftrightarrow{\mathcal{L}} s X(s)$  with ROC containing  $R$ **Proof:**

Inverse Laplace transform is given by

$$x(t) = \frac{1}{2\pi j} \int_{\sigma - j\infty}^{\sigma + j\infty} X(s) e^{st} ds$$

Differentiating above on both sides with respect to 't'

$$\frac{dx(t)}{dt} = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} \{sX(s)\} e^{st} ds$$

Comparing both equations  $sX(s)$  is the Laplace transform of  $\frac{dx(t)}{dt}$ .

### 8. Differentiation in the s-Domain:

**Statement:**

If  $x(t) \stackrel{\mathcal{L}}{\leftrightarrow} X(s)$  with ROC = R

then  $-tx(t) \stackrel{\mathcal{L}}{\leftrightarrow} \frac{dX(s)}{ds}$  with ROC = R

**Proof:**

Laplace transform is given by

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-st} dt$$

Differentiating above on both sides with respect to 's'

$$\frac{dX(s)}{ds} = \int_{-\infty}^{\infty} \{-tx(t)\} e^{-st} dt$$

Comparing both equations  $\frac{dX(s)}{ds}$  is the Laplace transform of  $-tx(t)$ .

### 9. Integration in the Time Domain:

**Statement:**

If  $x(t) \stackrel{\mathcal{L}}{\leftrightarrow} X(s)$  with ROC = R

then  $\int_{-\infty}^t x(\tau) d\tau \stackrel{\mathcal{L}}{\leftrightarrow} \frac{1}{s} X(s)$  with ROC containing  $R \cap \{Re\{s\} > 0\}$

**Proof:**

$$\int_{-\infty}^t x(\tau) d\tau = x(t) * u(t)$$

$$\mathcal{L}\left\{\int_{-\infty}^t x(\tau) d\tau\right\} = \mathcal{L}\{x(t) * u(t)\} = X(s) \cdot \mathcal{L}\{u(t)\} = X(s) \frac{1}{s}$$

## 10.The Initial and Final Value Theorems:

### *Statement:*

If  $x(t)$  and  $\frac{dx(t)}{dt}$  are Laplace transformable, and under the specific constraints that  $x(t)=0$  for  $t<0$  containing no impulses at the origin, one can directly calculate, from the

Laplace transform, the initial value  $x(0^+)$ , i.e.,  $x(t)$  as  $t$  approaches zero from positive values of  $t$ . Specifically the *initial -value theorem* states that

$$x(0^+) = \lim_{s \rightarrow \infty} sX(s)$$

Also, if  $x(t)=0$  for  $t<0$  and, in addition,  $x(t)$  has a finite limit as  $t \rightarrow \infty$ , then the *final-value theorem* says that

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$$

