

4.3 Modulation Scheme for Flying Capacitor Multilevel Converter (FCMC)

The modulation scheme used in **Flying Capacitor Multilevel Converters (FCMCs)** is crucial for controlling the switching devices to generate the desired output voltage waveform while maintaining balanced capacitor voltages. Various modulation strategies have been developed to optimize performance in terms of harmonic distortion, switching losses, and voltage balancing.

Below are the commonly used modulation schemes for FCMCs:

1. Phase-Shifted Pulse Width Modulation (PS-PWM)

Phase-Shifted PWM is a widely used modulation strategy for multilevel converters, particularly in FCMCs. This method involves using multiple carrier signals that are phase-shifted with respect to each other. Each phase-shifted carrier controls the switching of different levels in the converter.

- **How it works:**

- In an n -level FCMC, $(n-1)$ triangular carrier signals are generated, each phase-shifted by $360^\circ / (n-1)$ degrees.
- The reference waveform (typically sinusoidal) is compared with each of these phase-shifted carriers to control the switching devices.
- The result is a staircase output waveform with the desired number of voltage levels.

- **Advantages:**

- The phase shift between carrier signals ensures that the switching events are distributed evenly across the devices, which reduces the overall switching losses.
- The use of multiple carriers also helps in better harmonic performance.

- **Challenges:**

- PS-PWM does not inherently balance the flying capacitor voltages, so additional voltage balancing control is often required.

2. Level-Shifted Pulse Width Modulation (LS-PWM)

Level-Shifted PWM is another common modulation scheme for multilevel converters. It involves shifting the carriers at different voltage levels, rather than shifting them in time as with PS-PWM. There are several variations of LS-PWM, including:

- **In-phase disposition (PD) PWM**
- **Phase opposition disposition (POD) PWM**
- **Alternative phase opposition disposition (APOD) PWM**

How it works:

- In PD-PWM, all carrier signals are shifted in voltage, maintaining a constant phase. For an n -level FCMC, there are $n-1$ triangular carriers stacked vertically (voltage-shifted).

- The reference waveform is compared with each of these carriers, and based on the comparison, the switches are controlled to generate the desired voltage level.
- In POD-PWM, half of the carriers are inverted, while in APOD-PWM, every other carrier is inverted.
- **Advantages:**
 - This method is simpler and provides good harmonic performance.
 - It can generate balanced voltage levels across the capacitors when combined with appropriate control strategies.

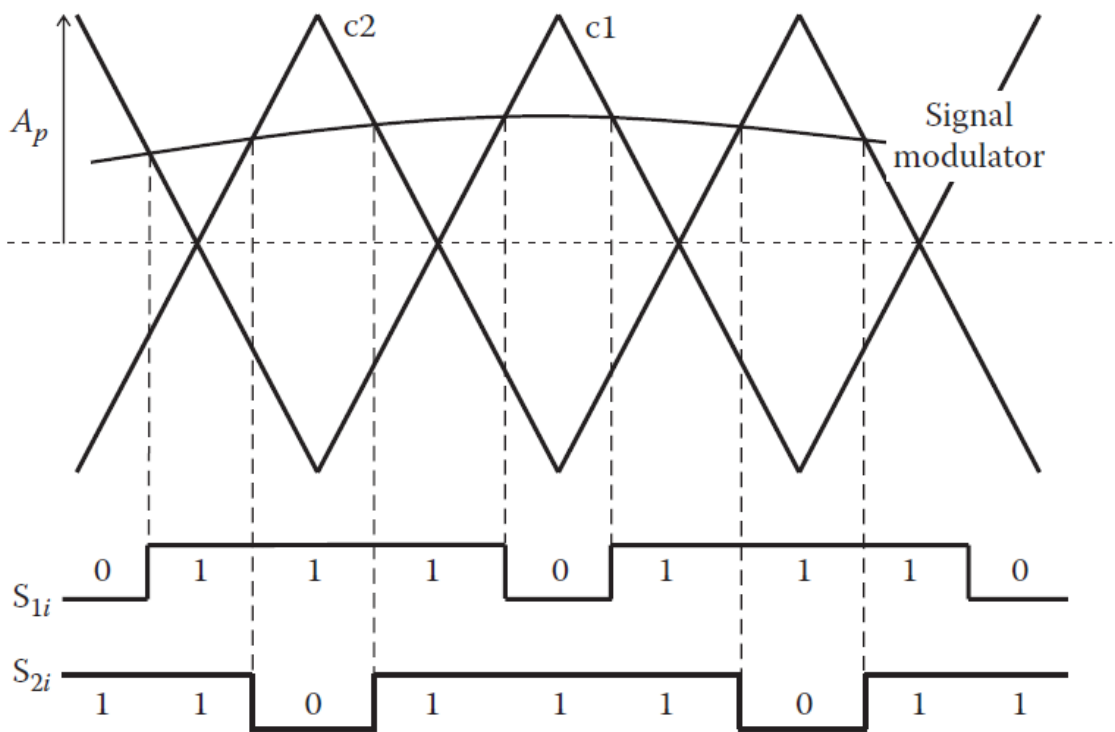


Fig 4.3.1 Switching functions when the modulating signal is positive

[Source: "Power Electronics" by P.S.Bimbira, Khanna Publishers Page: 454]

3. Space Vector Pulse Width Modulation (SVPWM)

Space Vector PWM (SVPWM) is a more advanced modulation technique that provides optimal control of the converter's output voltage by representing it as a vector in a 2D space. It is highly efficient and offers better control over the voltage output waveform compared to traditional PWM methods.

- **How it works:**

- SVPWM maps the reference voltage onto a vector space defined by the switching states of the converter.
- The space vector is then synthesized using the available switching states of the converter.
- The switching states are chosen in such a way as to minimize switching losses and improve harmonic performance.

- **Advantages:**

- SVPWM provides better voltage control, higher efficiency, and lower harmonic distortion compared to conventional PWM techniques.
- It also reduces the number of switching transitions, lowering switching losses.

- **Challenges:**

- The implementation of SVPWM in FCMCs is complex due to the increased number of switching states in multilevel converters.
- It requires sophisticated algorithms to balance the flying capacitor voltages.

4. Selective Harmonic Elimination (SHE)

Selective Harmonic Elimination (SHE) is a method that directly controls the switching angles to eliminate specific harmonic components from the output waveform. It is often used in applications where harmonic distortion needs to be minimized without high switching frequencies.

- **How it works:**

- SHE computes specific switching angles that are chosen to eliminate certain harmonics (typically lower-order harmonics like the 3rd, 5th, or 7th) from the output voltage waveform.
- The number of voltage levels in the converter allows for more flexibility in selecting switching angles that can effectively reduce harmonic distortion.

- **Advantages:**

- SHE can produce nearly perfect sinusoidal waveforms with minimal harmonic content, especially in high-power applications.
- It reduces the switching frequency, thus lowering switching losses.

- **Challenges:**

- The calculation of switching angles is complex, especially in real-time control systems.
- It requires precise control of capacitor voltages, and flying capacitor voltage balancing is not inherently handled by this method.

5. Neural Network-based and Predictive Control

With advances in control algorithms and artificial intelligence, **neural network-based** and **model predictive control** (MPC) techniques are being explored for FCMCs to enhance performance, especially in balancing flying capacitor voltages.

- **How it works:**

- Neural networks can be trained to optimize the switching pattern in real-time based on the output voltage, current, and capacitor voltage levels.
- MPC predicts the future behavior of the system and chooses the optimal switching sequence to minimize a cost function, which often includes capacitor voltage balancing, output voltage quality, and power losses.

- **Advantages:**

- These advanced control methods can significantly improve voltage balancing and waveform quality without requiring complex modulation techniques.
- They adapt to changing system dynamics, making them suitable for high-performance applications.

- **Challenges:**

- Neural network-based and MPC methods are computationally intensive, requiring powerful processors for real-time implementation. The design and training of neural networks or predictive models can be complex and time-consuming.