

Power flow solution using Gauss Seidel method

Algorithm of Gauss seidal method

Step1: Assume all bus voltage be $1 + j0$ except slack bus. The voltage of the slack bus is a constant voltage and it is not modified at any iteration

Step 2: Assume a suitable value for specified change in bus voltage which is used to compare the actual change in bus voltage between K^{th} and $(K+1)^{th}$ iteration

Step 3: Set iteration count $K = 0$ and the corresponding voltages are $V_1, V_2, V_3 \dots V_n$ except slack bus

Step 4: Set bus count $P = 1$

Step 5: Check for slack bus. It is a slack bus then goes to step 12 otherwise go to next step

Step 6: Check for generator bus. If it is a generator bus go to next step. Otherwise go to step 9

Step 7: Set $|V_P| = |V_P|_{\text{specified}}$ and phase of $|V_P|$ as the K^{th} iteration value if the bus P is a generator bus where $|V_P|_{\text{specified}}$ is the specified magnitude of voltage for bus P . Calculate reactive power rating $Q_P^{K+1} \text{ Cal} = (-1) \text{Imag} [(V_P)A (\sum Y_{pq} V_q^{K+1} + \sum Y_{pq} V_q^K \text{ for } q=1 \text{ to } n, q \neq P)]$

Step 8: If calculated reactive power is within the specified limits then consider the bus as generator bus and then set $Q_P = Q_P^{K+1} \text{ Cal}$ for this iteration go to step 10

Step 9: If the calculated reactive power violates the specified limit for reactive power then treat this bus as load bus.

If $Q_P^{K+1} \text{ Cal} < Q_P^{\text{min}}$ then $Q_P = Q_P^{\text{min}}$

$Q_P^{K+1} \text{ Cal} > Q_P^{\text{max}}$ then $Q_P = Q_P^{\text{max}}$

Step10: For generator bus the magnitude of voltage does not change and so for all iterations the magnitude of bus voltage is the specified value. The phase of the bus voltage can be calculated using

$$V_P^{K+1} \text{ temp} = 1 / Y_{PP} [(P - jQ_P / V_P^*) - \sum Y_{pq} V_q^{K+1} - \sum Y_{pq} V_q^K]$$

Step 11: For load bus the $(k+1)^{th}$ iteration value of load bus P voltage V_P^{K+1} can be calculated using $V_P^{K+1} \text{ temp} = 1 / Y_{PP} [(P - jQ_P / V_P^*) - \sum Y_{pq} V_q^{K+1} - \sum Y_{pq} V_q^K]$

Step 12: An acceleration factor α can be used for faster convergence. If acceleration factor is specified then modify the $(K+1)^{th}$ iteration value of bus P using

$$V_P^{\text{acc}K+1} = V_P^K + \alpha (V_P^{K+1} - V_P^K) \text{ then Set } V_P^{K+1} = V_P^{\text{acc}K+1}$$

Step 13: Calculate the change in bus- P voltage using the relation

$$\Delta V_P^{K+1} = V_P^{K+1} - V_P^K$$

Step 14: Repeat step 5 to 12 until all the bus voltages have been calculated. For this increment the bus count by 1 go to step 5 until the bus count is n

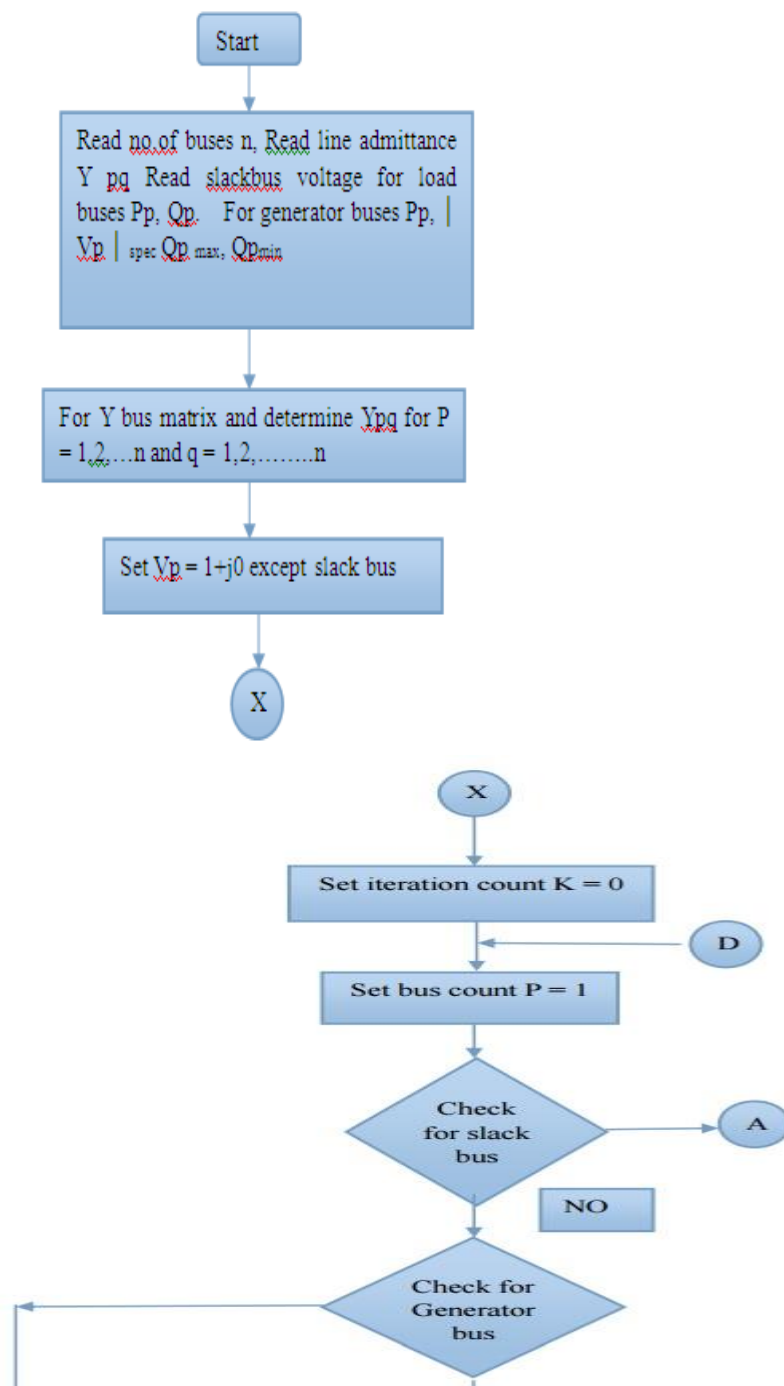
Step 15: Find the largest of the absolute value of the change in voltage

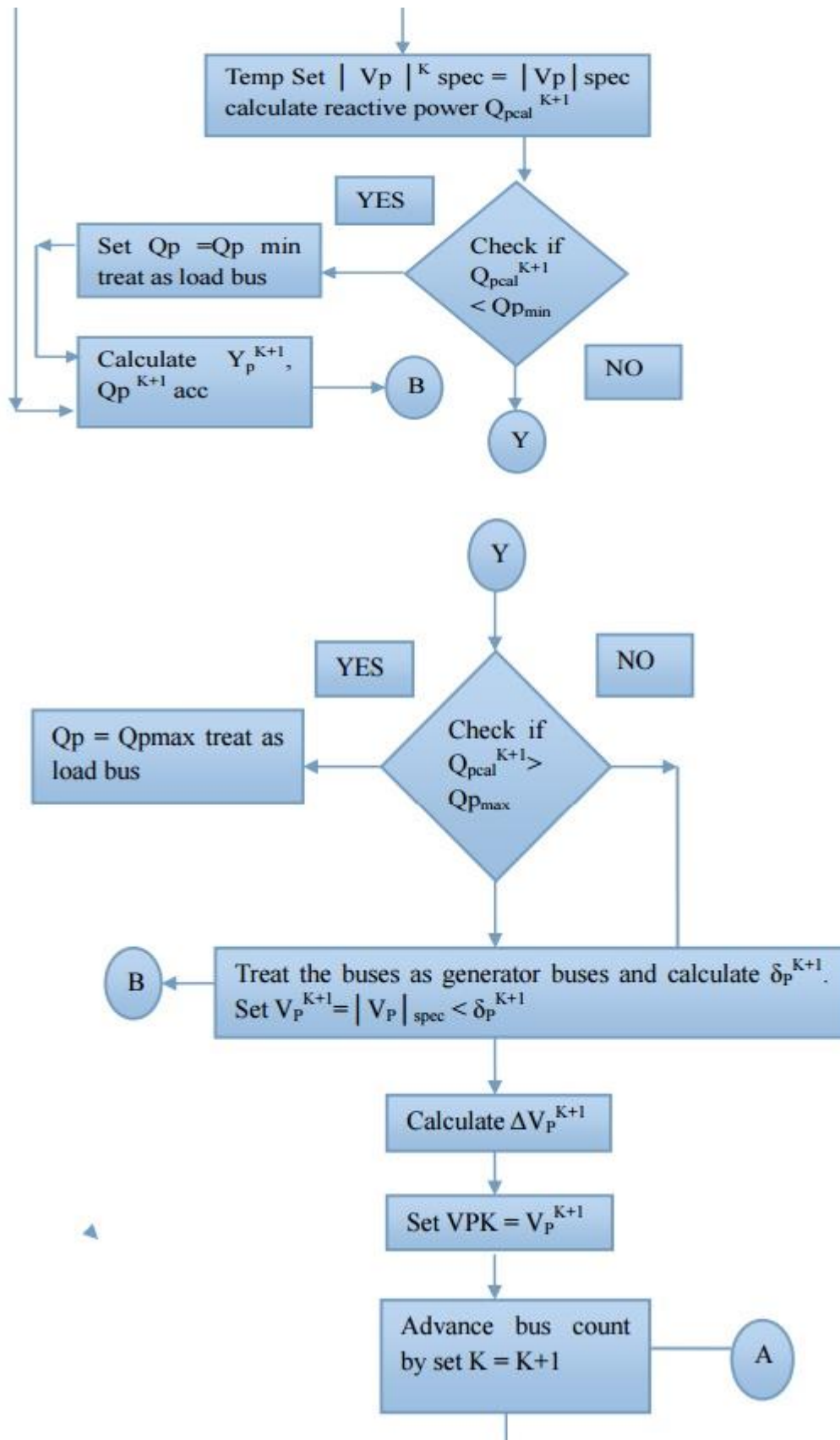
$$|\Delta V_1^{K+1}|, |\Delta V_2^{K+1}|, |\Delta V_3^{K+1}|, \dots, |\Delta V_n^{K+1}|$$

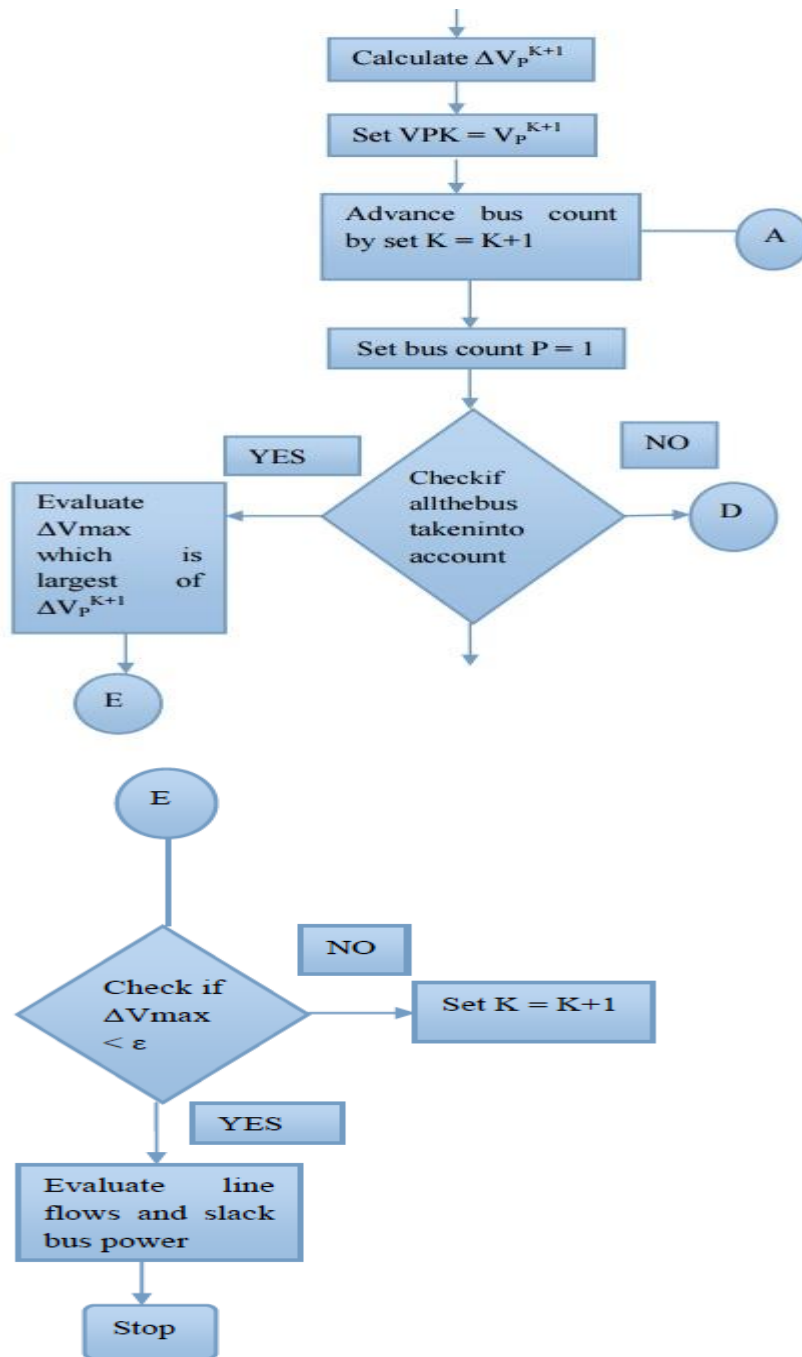
Let this largest value be the $|\Delta V_{\max}|$. Check this largest change $|\Delta V_{\max}|$ is less than pre specified tolerance. If $|\Delta V_{\max}|$ is less go to next step. Otherwise increment the iteration count and go to step 4

Step 16: Calculate the line flows and slack bus power by using the bus voltages.

Gauss - Seidal method flow chart







Advantages and disadvantages of Gauss-Seidel method

Advantages:

- Calculations are simple and so the programming task is less.
- The memory requirement is less.
- Useful for small systems

Disadvantages:

- Requires large no. of iterations to reach converge.
- Not suitable for large systems.
- Convergence time increases with size of the system