

NEWTON RAPHSON METHOD

Iterative solution using Newton-Raphson method – Algorithm

Step 1: Assume a suitable solution for all buses except the slack bus.

$$\text{Let } V_p = a+j0 \text{ for } P = 2,3,\dots,n \quad V_1 = a+j0$$

Step 2 : Set the convergence criterion = ϵ_0

Step 3 : Set iteration count $K = 0$

Step 4 : Set bus count $P = 2$

Step 5 : Calculate P_p and Q_p using n

$$P_p = \sum \{ e_p(e_p G_{pq} + f_p B_{qp}) + f_p(f_p G_{pq} - e_p B_{qp}) \} \quad q=1 \text{ to } n$$

$$Q_p = \sum \{ f_p(e_p G_{pq} + f_p B_{qp}) + e_p(f_p G_{pq} - e_p B_{qp}) \} \quad q=1$$

Step 6 : Evaluate $\Delta PPK = P_{\text{spec}} - PPK$

Step 7 : Check if the bus is the question is a PV bus. If yes compare QPK with the limits.

If it exceeds the limit fix the Q value to the corresponding limit and treat the bus as PQ for that iteration and go to next step (or) if the lower limit is not violated

$$\text{evaluate } |\Delta V_P|^2 = |V_{\text{spec}}|^2 - |V_{PK}|^2 \text{ and go to step 9}$$

Step 8: Evaluate $\Delta QPK = Q_{\text{spec}} - QPK$

Step 9 : Advance bus count $P = P+1$ and check if all buses taken in to account if not go to step 5

Step 10 : Determine the largest value of $|\Delta V_P|^2$

Step 11: If $\Delta V_P < \epsilon$ go to step 16

Step 12: Evaluate the element of Jacobin matrices J_1, J_2, J_3, J_4, J_5 and J_6

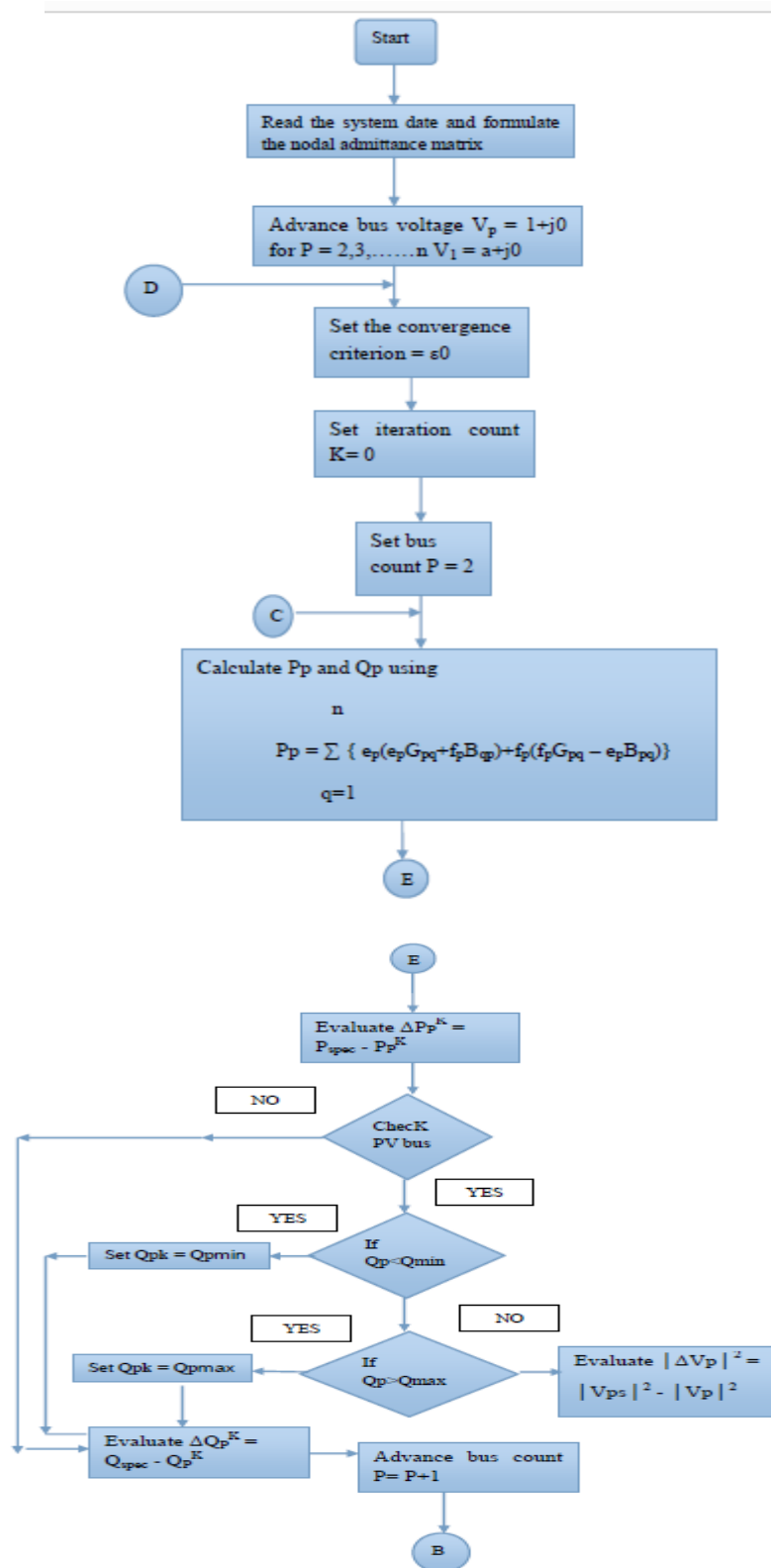
Step 13: Calculate Δe_{PK} and Δf_{PK}

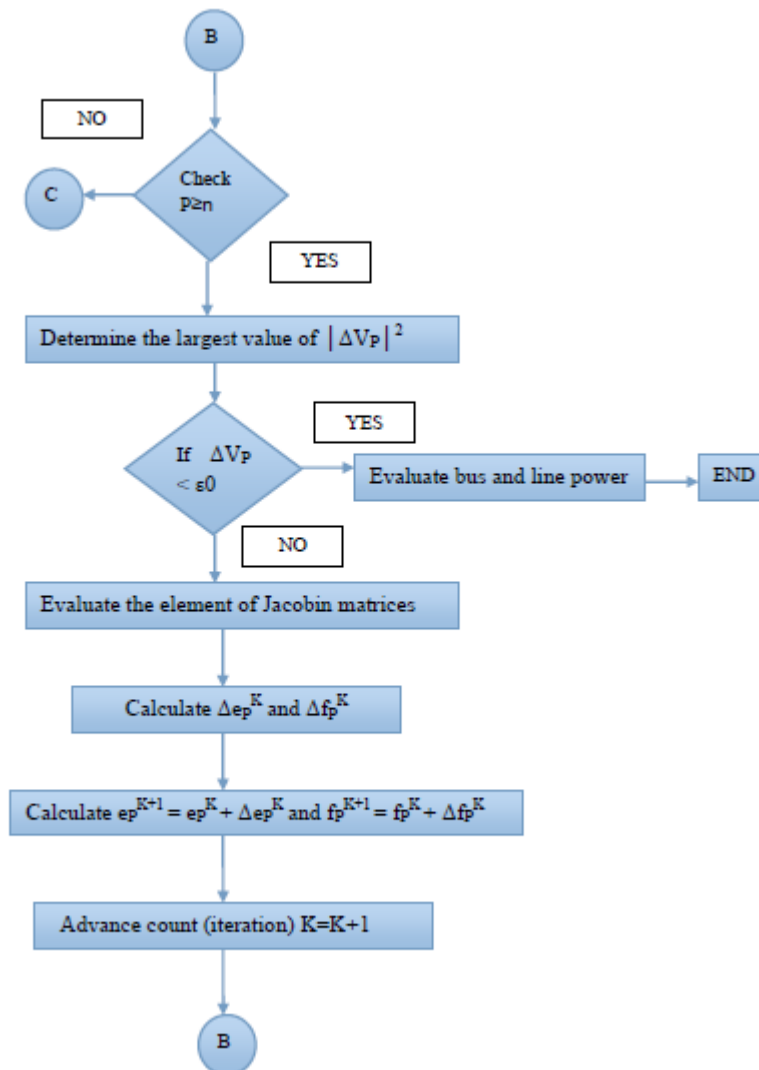
Step 14: Calculate $e_{PK+1} = e_{PK} + \Delta e_{PK}$ and $f_{PK+1} = f_{PK} + \Delta f_{PK}$

Step 15 : Advance count (iteration) $K=K+1$ and go to step 4

Step 16: Evaluate bus and line power and print the result

Iterative solution using Newton-Raphson method – Flow chart





Advantages and disadvantages of N.R method

Advantages:

Faster, more reliable and results are accurate, require less number of iterations;

Disadvantages:

Program is more complex, memory is more complex.