



**ROHINI**  
COLLEGE OF ENGINEERING & TECHNOLOGY  
(AUTONOMOUS)



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# Sample matrix inversion

C.PRISCILLA,AP/ECE

## Principle

- SMI is a **direct implementation of the Wiener solution**, using an estimated covariance matrix from finite data samples.
- The SMI beamformer replaces the true covariance matrix with a sample covariance matrix, yielding a practical implementation of optimal beamformers such as Wiener or MVDR (Capon) beamformers.

**1. Collect data snapshots**

$$\{\mathbf{x}(1), \mathbf{x}(2), \dots, \mathbf{x}(N)\}$$

**2. Estimate covariance matrix**

$$\hat{\mathbf{R}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}(n) \mathbf{x}^H(n)$$

**3. Invert covariance matrix**

$$\hat{\mathbf{R}}^{-1}$$

**4. Compute weight vector**

- Wiener or MVDR formula

**5. Apply beamformer**

$$y(n) = \mathbf{w}^H \mathbf{x}(n)$$

## SMI for Wiener Beamforming (MMSE)

Minimize mean square error:

$$J = E\{|d(n) - \mathbf{w}^H \mathbf{x}(n)|^2\}$$

Wiener solution

$$\mathbf{w}_{\text{opt}} = \mathbf{R}^{-1} \mathbf{p}$$

where:

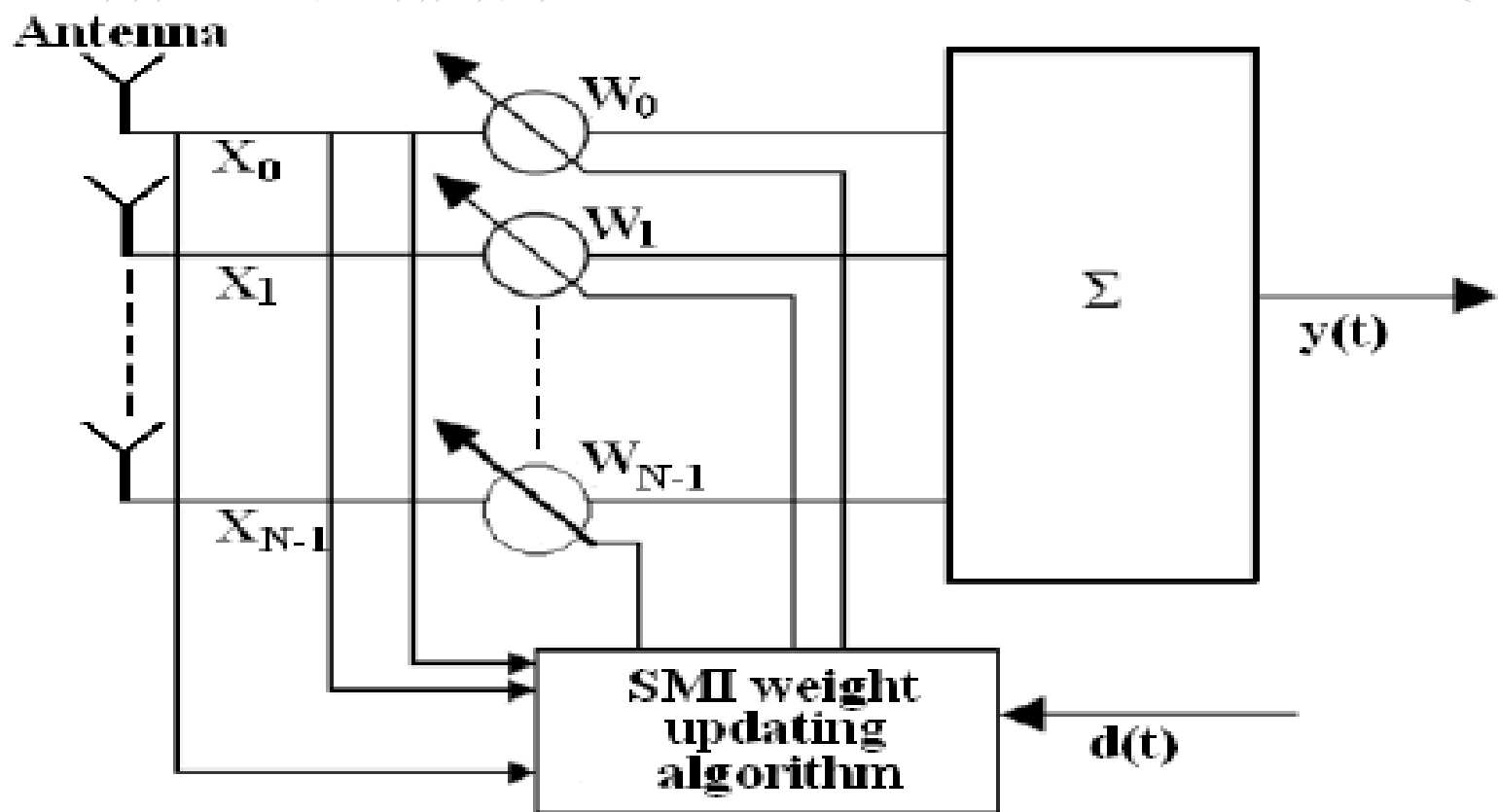
$$\mathbf{p} = E\{\mathbf{x}(n)d^*(n)\}$$

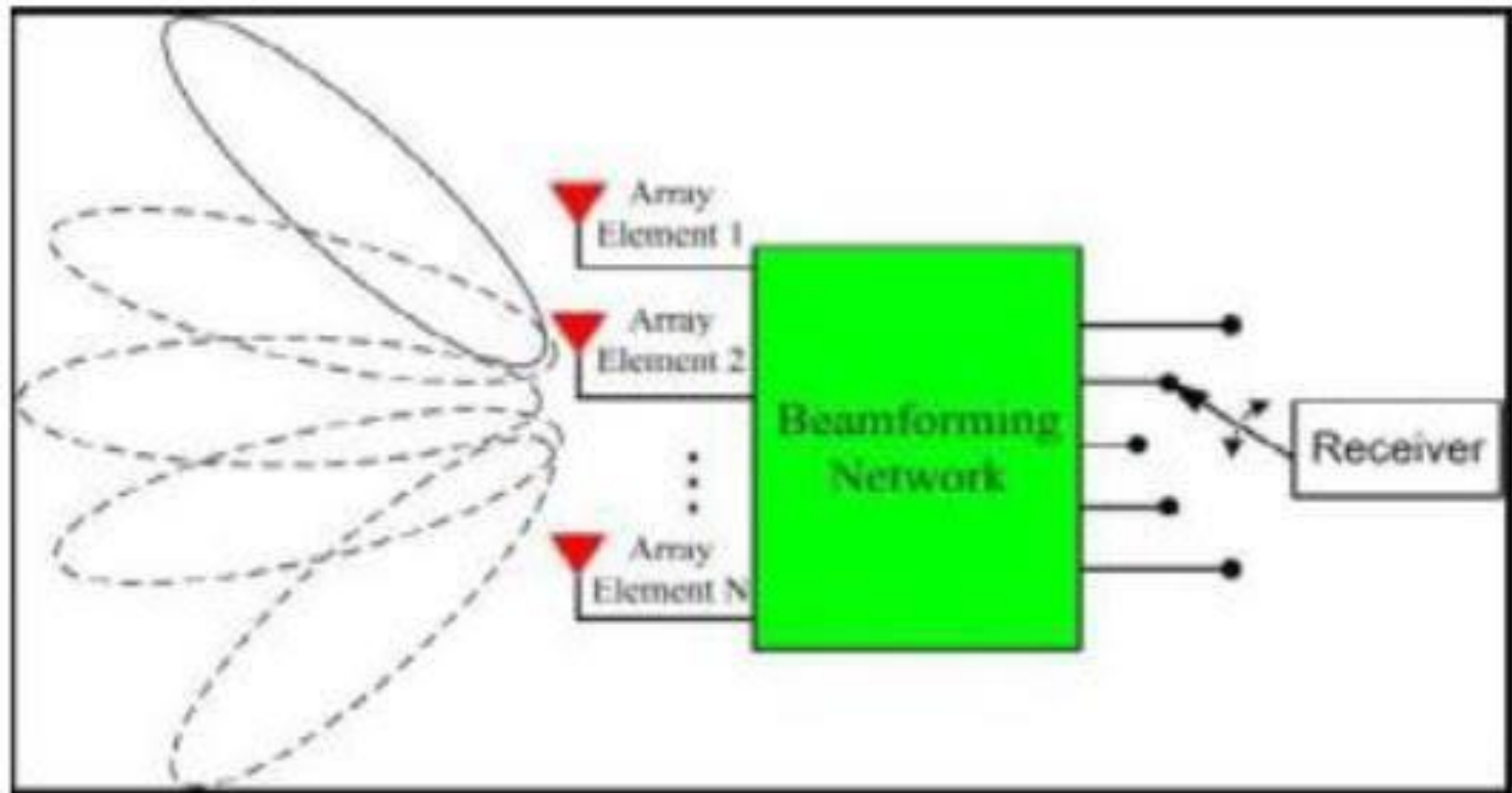
SMI approximation

$$\mathbf{w}_{\text{SMI}} = \hat{\mathbf{R}}^{-1} \hat{\mathbf{p}}$$

with:

$$\hat{\mathbf{p}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}(n)d^*(n)$$







## Applications

- Radar and sonar
- Smart antennas
- Direction-of-arrival (DOA) estimation preprocessing
- Wireless base stations